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Gaussian DAG models

► A linear structural equation model defines random variables X recursively via a directed acyclic graph G = (V, E) and Gaussian noise:

$$X_j = \sum_{i \in \mathrm{pa}(j)} \lambda_{ij} X_i + arepsilon_j, \quad arepsilon_j \sim \mathcal{N}(0, \omega_j).$$



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The vector X is again Gaussian with mean zero. Since G is acyclic, we can solve for the covariance matrix Σ:

$$\Sigma = (I - \Lambda)^{-\mathsf{T}} \Omega (I - \Lambda)^{-1}, \quad \text{with } \Lambda \in \mathbb{R}^{\mathsf{E}} \text{ and } \Omega = \operatorname{diag}(\omega).$$

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▶ All such matrices form the model $\mathcal{M}(G)$.

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- ► Almost all distributions in *M*(*G*) are faithful to *G*, i.e., do not satisfy more CI statements than the global Markov property.
- ▶ Model equivalence $\mathcal{M}(G) = \mathcal{M}(H)$ is combinatorially characterized: if and only if G and H have the same skeleton and v-structures.

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- Vertex-only colorings correspond to partial homoscedasticity [WD23].
- ► Coloring reduces Markov-equivalence classes which eases causal discovery.

▶ It follows from the recursive factorization and some linear algebra that

$$\omega_j = \frac{|\boldsymbol{\Sigma}_{j \cup \mathrm{pa}(j)}|}{|\boldsymbol{\Sigma}_{\mathrm{pa}(j)}|}, \quad \lambda_{ij} = \frac{|\boldsymbol{\Sigma}_{ij|\mathrm{pa}(j) \setminus i}|}{|\boldsymbol{\Sigma}_{\mathrm{pa}(j)}|}.$$

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► A set A is identifying for a vertex j resp. edge ij if

$$\omega_j = \omega_{j|A}(\Sigma)$$
 resp. $\lambda_{ij} = \lambda_{ij|A}(\Sigma)$

for all $\Sigma \in \mathcal{M}(G)$.

Theorem

Let G = (V, E) be a DAG. Then:

• $\omega_j = \omega_{j|A}(\Sigma)$ for every $\Sigma \in \mathcal{M}(G)$ if and only if $pa(j) \subseteq A \subseteq V \setminus \overline{de}(j)$. [WD23]

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► The polynomials $\operatorname{vcr}(i|A, j|B) = |\Sigma_A||\Sigma_B|(\omega_{i|A} - \omega_{j|B})$ resp. $\operatorname{ecr}(ij|A, kl|B) = |\Sigma_A||\Sigma_B|(\lambda_{ij|A} - \lambda_{kl|B})$ vanish on the model $\mathcal{M}(G, c)$ whenever c(i) = c(j) resp. c(ij) = c(kl) and A and B are identifying.

Model geometry

Theorem

For every colored DAG (G, c) the model $\mathcal{M}(G, c)$ is an irreducible variety and a smooth submanifold of PD_V. It is diffeomorphic to an open ball of dimension vc + ec (the number of vertex- and edge-color classes).

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The vanishing ideal $P_{G,c}$ of $\mathcal{M}(G,c)$ is $(I_G + I_c) : S_G$ where:

- ► $I_G = \langle |\Sigma_{ij|pa(j)}| : ij \notin E \rangle$ is the conditional independence ideal of G,
- ► $I_c = \langle vcr(i|pa(i), j|pa(j)) : c(i) = c(j) \rangle + \langle ecr(ij|pa(j), kl|pa(l)) : c(ij) = c(kl) \rangle$ is the coloring ideal of G,
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Resolves the colored generalization of a conjecture of Sullivant; see also [RP14].

Lemma

Let R, R' be rings, $S \subseteq R$ multiplicatively closed, and:

▶ maps $\phi : R \to R'$ and $\psi : R' \to S^{-1}R$ with $\psi \circ \phi = id_R$,

• for a prime ideal $I' = \langle f_1, \ldots, f_k \rangle$, write $\psi(f_i) = g_i/h_i$ and set $J = \langle g_i \rangle$.

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- Knowing a parametrization and generators for the vanishing ideal up to saturation is sufficient in practice for model distinguishability.
- ► Conceivable to extend to inequalities.

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Theorem ([WD23; STD10])



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► The example on the right colors vertices and edges. The generic matrix in the model satisfies 1 ⊥⊥ 4 | 5. No faithful distribution!



Theorem ([WD23])

If (G, c) and (H, c) are vertex-colored DAGs, then $\mathcal{M}(G, c) = \mathcal{M}(H, c)$ if and only if G and H are Markov-equivalent and $pa_G(j) = pa_H(j)$ for all $j \in V$ with $|c^{-1}(j)| \ge 2$.

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Theorem

If (G, c) and (H, d) are edge-colored DAGs, then $\mathcal{M}(G, c) = \mathcal{M}(H, d)$ implies that (G, c) and (H, d) are similar. In particular, if every edge is in a color class of size at least 2, edge directions are uniquely determined.

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