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Gaussian DAG models

 \triangleright A linear structural equation model defines random variables X recursively via a directed acyclic graph $G = (V, E)$ and Gaussian noise:

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All such matrices form the model $\mathcal{M}(G)$.

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- Almost all distributions in $M(G)$ are faithful to G, i.e., do not satisfy more CI statements than the global Markov property.
- \blacktriangleright Model equivalence $\mathcal{M}(G) = \mathcal{M}(H)$ is combinatorially characterized: if and only if G and H have the same skeleton and v-structures.

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- \triangleright Vertex-only colorings correspond to partial homoscedasticity [\[WD23\]](#page-40-0).
- \triangleright Coloring reduces Markov-equivalence classes which eases causal discovery.

 \blacktriangleright It follows from the recursive factorization and some linear algebra that

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\omega_j = \frac{|\Sigma_{j \cup \mathrm{pa}(j)}|}{|\Sigma_{\mathrm{pa}(j)}|}, \quad \lambda_{ij} = \frac{|\Sigma_{ij| \mathrm{pa}(j) \setminus i}|}{|\Sigma_{\mathrm{pa}(j)}|}.
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 \triangleright A set A is identifying for a vertex *j* resp. edge *ij* if

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\omega_j = \omega_{j|A}(\Sigma) \text{ resp. } \lambda_{ij} = \lambda_{ij|A}(\Sigma)
$$

for all $\Sigma \in \mathcal{M}(G)$.

Theorem

Let $G = (V, E)$ be a DAG. Then:

 $\triangleright \omega_j = \omega_{j|A}(\Sigma)$ for every $\Sigma \in \mathcal{M}(G)$ if and only if $\text{pa}(j) \subseteq A \subseteq V \setminus \overline{\text{de}}(j)$. [\[WD23\]](#page-40-0)

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 \blacktriangleright The polynomials $\text{ver}(i|A, j|B) = |\Sigma_A||\Sigma_B|(\omega_{i|A} - \omega_{i|B})$ resp. $\text{ecr}(ij|A, k||B) = |\Sigma_A||\Sigma_B|(\lambda_{ij|A} - \lambda_{k||B})$ vanish on the model $\mathcal{M}(G, c)$ whenever $c(i) = c(i)$ resp. $c(i) = c(k)$ and A and B are identifying.

Model geometry

Theorem

For every colored DAG (G, c) the model $\mathcal{M}(G, c)$ is an irreducible variety and a smooth submanifold of PD_V. It is diffeomorphic to an open ball of dimension $vc + ec$ (the number of vertex- and edge-color classes).

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The vanishing ideal $P_{G,c}$ of $\mathcal{M}(G,c)$ is $(I_G + I_c)$: S_G where:

- $I_G = \langle |\Sigma_{ij|pa(j)}| : ij \notin E \rangle$ is the conditional independence ideal of G,
- $I_c = \langle \text{vcr}(i|pa(i), j|pa(j)) : c(i) = c(j) \rangle + \langle \text{ecr}(ij|pa(j), kl|pa(l)) : c(ij) = c(kl) \rangle$ is the coloring ideal of G,
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Resolves the colored generalization of a conjecture of Sullivant; see also [\[RP14\]](#page-40-1).

Lemma

\n- maps
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\phi : R \to R'
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 and $\psi : R' \to S^{-1}R$ with $\psi \circ \phi = \text{id}_R$,
\n- for a prime ideal $I' = \langle f_1, \ldots, f_k \rangle$, write $\psi(f_i) = \frac{\varepsilon_i}{h_i}$ and set $J = \langle g_i \rangle$.
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For example, ϕ = parametrization of $\mathcal{M}(K_n)$, ψ = parameter identification map and $I' =$ linear equations on parameters from missing edges and color classes.

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- \blacktriangleright Knowing a parametrization and generators for the vanishing ideal up to saturation is sufficient in practice for model distinguishability.
- \triangleright Conceivable to extend to inequalities.

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 \blacktriangleright The example on the right colors vertices and edges. The generic matrix in the model satisfies $1 \perp 4$ | 5. No faithful distribution!

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If (G, c) and (H, c) are vertex-colored DAGs, then $\mathcal{M}(G, c) = \mathcal{M}(H, c)$ if and only if G and H are Markov-equivalent and $\text{pa}_G(j) = \text{pa}_H(j)$ for all $j \in V$ with $|c^{-1}(j)| \geq 2$.

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Theorem

If (G, c) and (H, d) are edge-colored DAGs, then $\mathcal{M}(G, c) = \mathcal{M}(H, d)$ implies that (G, c) and (H, d) are similar. In particular, if every edge is in a color class of size at least 2, edge directions are uniquely determined.

References

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